

blocks for controlled cooling thereof, wherein each of the heating and cooling devices is in communication with the controller.

4. (Original) The apparatus of claim 3, wherein the heating device heats the hot reaction blocks according to the predetermined temperature profile.
5. (Original) The apparatus of claim 1, wherein the predetermined temperature profile includes an initial temperature and a final temperature, the predetermined temperature profile being defined by the initial temperature and the final temperature.
6. (Original) The apparatus of claim 1, wherein the predetermined sampling interval includes a study start time and a study stop time with the sampling interval being the time period beginning with the start time and ending with the stop time of the study.
7. (Original) The apparatus of claim 1, wherein the robotic device moves in three dimensions relative to the plurality of reaction blocks so as to permit the robotic device to grasp and transfer the plurality of reaction vessels.
8. (Original) The apparatus of claim 1, wherein the robotic device has a gripping mechanism for gripping and transferring one reaction vessel from the hot reaction block to the cold reaction block at the predefined transfer time.
9. (Original) The apparatus of claim 8, wherein the gripping mechanism is operated by toggling a predetermined pressure between first and second lines such that the gripping mechanism closes to securely engage one reaction vessel for transfer from the hot reaction block to the cold reaction block when a pressure is applied to the first line with the second line being vented, the gripping mechanism opening to release the one

reaction vessel when the pressure is applied to the second line with the first line being vented.

10. (Original) The apparatus of claim 8, wherein the gripping mechanism includes a first finger and a second opposing finger with a space therebetween, one reaction vessel being disposed within the space and held between the first and second fingers during the transfer of the one reaction vessel from the hot reaction block to the cold reaction block.
11. (Original) The apparatus of claim 1, wherein the controller includes a master clock and a count-down clock, the master clock displaying the sampling interval for the study and the count-down clock counting down the time before the next transfer of one of the reaction vessels.
12. (Original) The apparatus of claim 1, wherein the master controller includes a user interface for inputting the predetermined temperature profile and the predetermined sampling interval.
13. (Original) The apparatus of claim 1, further including:
 - a temperature control device operatively connected to one or more of the hot and cold reaction blocks for controlling a temperature of each of the hot and cold reaction blocks, the temperature control device being in communication with the controller, and
 - a temperature monitoring device for monitoring the temperature within at least one of the hot and cold blocks, the temperature monitoring device being in communication with the controller so as to provide the controller with temperature data representing the temperature of one or more of the hot and cold blocks.

14. (Previously Presented) The apparatus of claim 13, wherein the temperature control device comprises one of a single loop, dual loop, and multi-loop temperature controller.
15. (Previously Presented) The apparatus of claim 13, wherein the temperature monitoring device is a resistance temperature detector.
16. (Previously Presented) An automated apparatus for performing reaction kinetics studies, the apparatus comprising:
 - a plurality of reaction blocks including at least one hot reaction block for heating one or more reaction vessels and at least one cold reaction block for cooling the one or more reaction vessels after heating thereof;
 - a robotic device for transferring one reaction vessel from one hot reaction block to one cold reaction block; and
 - a controller having a user interface for inputting a predetermined temperature profile and a predetermined sampling interval, the controller being in communication with the plurality of reaction blocks and the robotic device so as to instruct the robotic device to transfer one reaction vessel from one hot reaction block to one cold reaction block at a predefined transfer time within the predetermined sampling interval, the predetermined temperature profile representing the temperature of at least one of the hot reaction blocks over a time period of the study;
 - wherein the predetermined temperature profile is an isothermal temperature profile.
17. (Canceled)
18. (Previously Presented) An automated apparatus for performing reaction kinetics studies, the apparatus comprising:

a plurality of reaction blocks including at least one hot reaction block for heating one or more reaction vessels and at least one cold reaction block for cooling the one or more reaction vessels after heating thereof;

a robotic device for transferring one reaction vessel from one hot reaction block to one cold reaction block;

a controller having a user interface for inputting at least (1) a number of reaction vessels for the study, (2) a first predetermined temperature profile and a second predetermined temperature profile, (3) a predetermined study time period beginning with a start time and ending with a stop time, and (4) a selected kinetics model, wherein the controller is in communication with the hot and cold reaction blocks and the robotic device, the controller including an operating system which instructs the robotic device to transfer the plurality of reaction vessels from one hot reaction block to one cold reaction block at predefined transfer times and wherein at least one of the hot reaction blocks is heated according to the first predetermined temperature profile over the study time period, the controller collecting and storing kinetics data for each reaction vessel transfer, the kinetics data at least including a temperature of the hot reaction block at each transfer time and a sampling time when each reaction vessel transfer from the hot reaction block to the cold reaction block occurred; and

wherein the kinetics data is fitted to the selected kinetics model inputted by the user to generate a representative temperature vs. time graph, wherein the first predetermined temperature profile is a nonisothermal temperature profile and the second predetermined temperature profile comprises an isothermal temperature profile.

19. (Previously Presented) The apparatus of claim 20, wherein the hot reaction block has a number of openings formed therein for receiving a

number of reaction vessels, the hot reaction blocks being connected to one or more heating devices with one or more temperature control devices being associated with the one or more heating devices for setting the temperature of one or more hot reaction blocks and wherein each cold reaction block has a number of openings formed therein for receiving a number of reaction vessels, the cold reaction blocks being connected to one or more cooling devices with one or more temperature control devices being associated with the one or more cooling devices.

20. (Previously Presented) An automated apparatus for performing reaction kinetics studies, the apparatus comprising:

a plurality of reaction blocks including at least one hot reaction block for heating one or more reaction vessels and at least one cold reaction block for cooling the one or more reaction vessels after heating thereof;

a robotic device for transferring one reaction vessel from one hot reaction block to one cold reaction block;

a controller having a user interface for inputting at least (1) a number of reaction vessels for the study, (2) a first predetermined temperature profile and a second predetermined profile, (3) a predetermined study time period beginning with a start time and ending with a stop time, wherein the controller is in communication with the hot and cold reaction blocks and the robotic device, the controller including an operating system which instructs the robotic device to transfer the plurality of reaction vessels from one hot reaction block to one cold reaction block at predefined transfer times and wherein at least one of the hot reaction blocks is heated according to the first predetermined temperature profile over the study time period, the controller collecting and storing kinetics data for each reaction vessel transfer, the kinetics data at least including a temperature of the hot reaction block at each

entering a first input using the user interface, the first input corresponding to a number of reaction vessels used in the study;

entering a second input using the user interface, the second input corresponding to an isothermal temperature profile which represents the temperature of at least one of the hot reaction blocks over a time period of the study;

entering a third input using the user interface, the third input corresponding to a nonisothermal temperature profile which represents the temperature of at least one of the hot reaction blocks over a time period of the study;

entering a fourth input using the user interface, the fourth input corresponding to the time period of the study beginning with a start time and ending with a stop time;

transferring the reaction vessels at predefined transfer times, the predefined transfer times being calculated using the first and fourth inputs, each reaction vessel being transferred from one hot reaction block to one cold reaction block by the robotic device which receives command signals from the controller;

collecting kinetics data including at least a temperature of the hot reaction block at each transfer time and a sampling time indicating when each reaction vessel transfer occurred; and

fitting the kinetics data to an inputted kinetics model.

29. (Previously Presented) The method of claim 32, wherein transferring the reaction vessels comprises:

sending a signal from the controller to the robotic device causing a gripping mechanism of the robotic device to be positioned at a predefined coordinate location relative to one of the hot reaction blocks where the gripping mechanism is instructed to securely grasp one of the

34. (Previously Presented) The method of claim 31, further including:
entering a sixth input using the user interface, the sixth input being a value for the number of reaction vessels to be transferred at each predefined transfer time; and
transferring the reaction vessels according to the sixth input.
35. (Previously Presented) The method of claim 32, wherein the fifth input is selected from the group consisting of a logarithmic fit, a reciprocal fit, a linear fit, an exponential fit, and a power function of time fit.
36. (Previously Presented) A method of performing reaction kinetics studies and collecting data using an automated apparatus, the method comprising:
providing the automated apparatus, the apparatus including:
a plurality of reaction blocks including at least one hot reaction block for heating one or more reaction vessels and at least one cold reaction block for cooling the one or more reaction vessels after heating thereof;
a robotic device for transferring one reaction vessel from one hot reaction block to one cold reaction block;
a controller having a user interface and being in communication with the robotic device;
entering a first input using the user interface, the first input corresponding to a number of reaction vessels used in the study;
entering a second input using the user interface, the second input corresponding to a predetermined temperature profile which represents the temperature of at least one of the hot reaction blocks over a time period of the study;
entering a third input using the user interface, the third input corresponding to the time period of the study beginning with a start time

